

7

7

7

Describe three primary ways to load a program in

Write a note on microcontroller versus general

purpose microprocessor.

AVR microcontroller.

(b) Explain AVR status register in detail.

3	Answer the following:		
	(a)	Write the steps to program the AVR microcontroller with Timer0 in normal mode.	7
	(b)	Write an algorithm to program the AVR microcontroller with Counter1 in normal mode.	7
		OR	
3	Ans	ower the following:	14
	(a)	Write a note on Interrupt versus Polling for AVR microcontroller.	7
	(b)	Write an algorithm to program the AVR microcontroller to receive data serially.	7
4	Ans	ower the following:	14
	(a)	A door sensor is connected to Bit-1 of Port-B, and an LED is connected to Bit-7 of Port-C. Write an AVR C-program to monitor the door sensor and, when it opens, turn ON the LED.	7
	(b)	Write an AVR C-program to toggle only the PORTB.4 bit continuously every 2 ms. Use Timer-1, Normal Mode, and no prescaler to create the delay. Assume XTAL=8 MHz.	7
5	Ans	wer the following: (any two)	14
	(a)	Write an AVR C-program to receive bytes of data serially and put them on Port-B. Use receive complete interrupt instead of polling method.	7
	(b)	Write an AVR C-program to read the keypad and send the result to Port-D. PC0 - PC3 connected to columns. PC4 - PC7 connected to rows.	7
	(c)	Write an AVR C-program to display the message "HELLO WORLD" on 16×2 LCD. Use 8-bit data to interface an LCD to the AVR.	7
	(d)	A switch is connected to pin PORTA.7. Write an AVR C-program to monitor the status of SW and perform the following: (i) If SW = 0, the stepper motor moves clockwise. (ii) If SW = 1, the stepper motor moves counterclockwise.	7

[50]